Machine Learning Supervised learning 1

#### S. Nõmm

<sup>1</sup>Department of Software Science, Tallinn University of Technology

#### 16.02.2021

# Supervised learning

Is a task of inferring function (training a model) on the basis of labeled training data. The goal is to construct a function (train a model) which would mimic (in a certain sense) behaviour of the underling process.

- Regression: Dependent variable (continuous) plays a role of labels.
  - Linear
  - Nonlinear
  - Application of trees and SVM for regression.
  - Advanced methods like Neural Networks, etc.
- Classification labels are discrete (categorical values).
  - k-nearest neighbours.
  - Decision trees.
  - Support Vector Machines.
  - Neural networks.
  - Ensemble (committee).
  - Boosted techniques.
- Markov models.

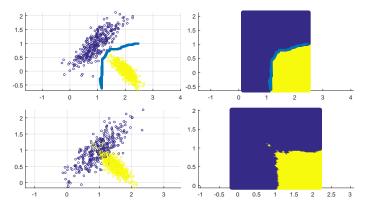
# Classification

- Learning existing grouping on the basis of the labeled (training) set.
- The goal is to generate (choose the structure and train) a model which would mimic existing grouping.
- Based on the features of the element model should estimate which class element belong to or estimate value of dependent variable.
- Unlike the case of unsupervised learning miss classification may be precisely measured.
- What is the cost of miss classification or error in the case of regression?

k - nearest neighbours (k-NN)

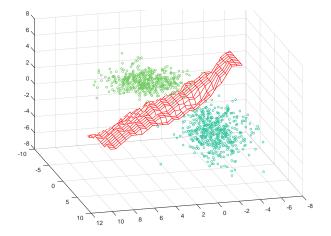
- Let D denote training (labeled) data set.
- For each unlabeled point (point to be classified)
  - ▶ Find *k* nearest neighbours.
  - Assign mode (majority) label of k nearest neighbours.

## k - nearest neighbors, geometric interpretation, 2D



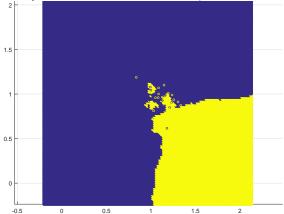
- Decision boundary (decision surface) (statistical classification with two classes) is a hypersurface that partitions the data set into two subsets, one for each class.
- Classifier tries to learn (construct) decision boundary that will lead minimal empirical error.

k - nearest neighbors, 3D



# Accuracy

During the training (learning) process classifier tries to learn (construct) decision boundary that will lead minimal empirical error.



How good is trained classifier?

#### Validation

• Overall accuracy and Confusion matrix (table), computed for the validation subset, are the goodness parameters of trained classifier.

	Predicted Class 1	Predicted class $2$
Actual class 1	58	2
Actual class 2	6	134

• How reliable these parameters are ?

## Cross validation

- Non-exhaustive do not use all possible ways of splitting into training and validation sets
  - ▶ k fold.
  - Holdout.
  - Repeated random sub-sampling.
- Exhaustive: use all possible ways to divide the data set into training and validation sets
  - Leave p-out cross validation.
  - Leave one out cross validation.

# Cross validation: k- fold validation

- Divide the training data (after removing test data) randomly into k folds.
- Perform following k experiments:
  - Compose the training data by concatenating k-1 folds leaving one fold out.
  - Train the model on those k-1 folds
  - Test it on the left-out fold
  - Record the result
- Report the average of the k experiments.

# Learning: Underfitting and overfitting

- Underfitting the learned function is too simple In the context of human learning: underfitting similar to the case when one learns too little.
- *Overfitting* the learned function is too complex In the context of human learning: overfitting is more similar to memorizing than learning.

#### Feature selection for classification

• Case of categorical data: Gini Index or Entropy. Value specific:

$$G(v_i) = 1 - \sum_{j=1}^k p_j^2;$$
  $E(v_i) = -\sum_{j=1}^k p_j \log_2(p_j)$ 

where  $p_j$  is the fraction of data points containing attribute value  $v_i$ . Lower values of Gini index or Entropy imply greater discriminative power.

• Feature specific: Let  $n_i$  is the number of data points taking value  $v_i$ . Feature specific Gini index is defined as the weighted average value of value specific Gini indexes.

$$G = \sum_{i=1}^{r} \frac{n_i G(v_i)}{n}$$

where r is the number of different values  $v_i$  and  $n = \sum n_i$ .

• Feature specific values of Entropy are computed in the similar way.

Feature selection for classification II

• Case of numeric data: Fisher's score

$$F = \frac{\sum_{j=1}^{k} p_j (\mu_j - \mu)^2}{\sum_{j=1}^{k} p_j \sigma_j^2}$$

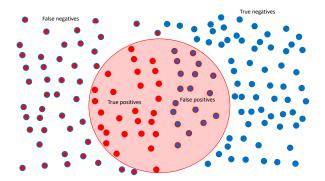
Greater values imply greater discriminative power of the variable.Wrapper methods.

# Classification model goodness!

- How good is the model?
- What is the goal of modeling?

## Classification outcome

- Consider binary classifier.
- In the data set there are two classes: Positive (P) and negative (N)
- Outcomes of the classification: True positive, true negative, false positive (type I error), false negative(type II error).



# Context of information retrieval

NB! Observe notions!

- Relevant elements of the data set. One is interested to find (retrieve elements of the certain class).
- Precision is defined as:

$$\text{precision} = \frac{|\text{relevant} \cap \text{retrieved}|}{|\text{retrieved}|}$$

• Recall (sensitivity, hit rate, True Positive Rate) is defined as:

$$\text{recall} = \frac{|\text{relevant} \cap \text{retrieved}|}{|\text{relevant}|}$$

#### Context of classification I

Denote: tp - true positive, tn - true negative, fp - false positive and fn - false negative.

• Precision (positive predictive value):

$$Precision = \frac{tp}{tp + fp}$$

• Recall (sensitivity, hit rate, TPR):

$$\text{Recall} = \frac{tp}{tp + fn}$$

• True negative rate (Specificity, selectivity):

$$TNR = \frac{tn}{tn + fp}$$

Accuracy:

Accuracy = 
$$\frac{tp + tn}{tp + tn + fp + fn}$$

Predicted positive condition rate

Predicted positive condition  $rate = \frac{tp + fp}{tp + tn + fp + fn}$ 

# F-measure not to be confused with similarly named values!!!

Frequently referred as  $F_1$ -score ... is harmonic average of precision and recall.

۲

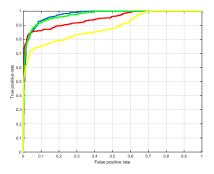
$$F = 2 * \frac{\text{precisionrecall}}{\text{precision} + \text{recall}}$$

• More general definition:

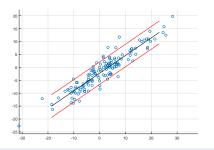
$$F_{\beta} = (1 + \beta^2) \frac{\text{precisionrecall}}{\beta^2 \text{precision} + \text{recall}}$$

#### Receiver Operating Characteristic or ROC curve

- Let  $\mathcal{D} = \{x_i, y_i\}$  is the labeled data set.
- Assume also that  $\delta(x)=\mathbb{I}(f(x)>\tau)$  decision rule. f(x) is the confidence function and  $\tau$  threshold parameter
- Each particular value of  $\tau$  corresponds to a certain decision rule.
- For each decision rule one may compute recall and false positive rate.
- Associate recall values with the axis Y and false positive rate values with axis X.



# Linear regression: probably the oldest machine learning technique



- Find linear correlation coefficient.
- Compute coefficients of the linear equation

$$\hat{y} = ax + b$$

Evaluate the model

• In multivariate case it is required to identify coefficients of the model

$$\hat{y} = a_1 x_1 + a_2 x_2 + \ldots + a_n x_n + b.$$

This leads the necessity to choose variables (perform model building).

#### Linear regression

• Correlation coefficient.

$$\rho = \frac{\sum_{i=1}^{n} (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^{n} (x_i - \bar{x})^2 \sum_{i=1}^{n} (y_i - \bar{y})^2}}$$

where, n - is the sample size, x and y are the variable of interest.

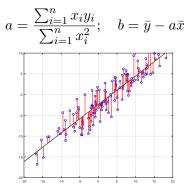
- $-1 \le \rho \le 1$
- Assumption there are exist  $\alpha$  and  $\beta$  such that for any  $i = 1, \ldots, n$  $y_i = \alpha x_i + \beta + \varepsilon_i$  holds. Assumption:  $\varepsilon$  is sufficiently small normally distributed.
- The goal of regression is to find estimates of the coefficients  $\alpha$  and  $\beta,$  such that for a and b

$$y_i = ax_i + b + \hat{\varepsilon}_i$$

sum of squares of  $\hat{\varepsilon}_i$  would be minimal. NB! notation  $\hat{\alpha}$  and  $\hat{\beta}$  is also widely use.

#### Least squares method

Least squares method:



For an arbitrary number of variables:

$$y = b_1 x_1 + \ldots + b_n x_n + b_0$$

then

$$\hat{b} = (X^T X)^{-1} X^T y.$$

where each row of matrix X is input vector with 1 in the first position.

## Model validation

- Coefficient of determination  $R^2$  and adjusted  $R^2$ .
- Significance of the model and model coefficients.
- Verify assumption that residuals are normally distributed.
- Residual sum squares. RSS =  $\sum_{i=1}^{N} (y_i x_i^T x_i \beta)^2$ .
- Sum squares of the regression  $SSR = \sum_{i=1}^{N} (\hat{y}_i \bar{y}\beta)^2$ .
- Total sum squares or sum of squares about the mean  $SSR = \sum_{i=1}^{N} (y_i \bar{y}\beta)^2$ .
- $R^2$  computed as the ratio of Sum squares of the regression to total sum squares or one minus ratio of Residual sum squares to total sum squares whereas adjusted  $R^2$  is one minus ratio of residual sum squares computed for n-1 to Total sum squares for n-pobservation points.

# Statistical hypothesis testing (brief reminder I)

- Assumption about a parameter of population is a statistical hypothesis.
- Usually a pair of hypothesis is stated  $(H_0, H_1)$ , notation  $(H_0, H_a)$ .
  - ► *H*<sup>0</sup> the null hypothesis usually states that there is no statistically significant relationship between two phenomena.
  - $H_1$  the alternative hypothesis usually states the opposite to the  $H_0$ .
- Choose and compute test statistic and rejection rule.
- Interpret the results.
- What can possibly go wrong?

# Statistical hypothesis testing (brief reminder II)

	Accept $H_0$	Reject $H_0$
$H_0$ is true	Correct	Type 1 Error
$H_0$ is false	Type II Error	Correct

# Model building (feature selection)

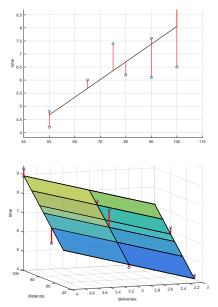
Let us suppose that observed process has p independent variables  $x_1, \ldots, x_p$  and one dependent variable y. Should one build the regression equation using all p variables or not?

- Are all the variables  $x_1, \ldots, x_p$  uncorrelated?
- Which subset of variables result in a "better" model?
- How to prove that as a result of adding or deleting a variable model quality has improved?

# "Butler tracking company" example

- Independent variables: Distance to drive and number of parcels to deliver. Dependent variable: time.
- Distances to drive for each assignment: 100, 50, 100, 100, 50, 80, 75, 65, 90, 90.
- Number of parcels to deliver: 4, 3, 4, 2, 2, 2, 3, 4, 3, 2
- Time in hours: 9.3, 4.8, 8.9, 6.5, 4.2, 6.2, 7.4, 6, 7.6, 6.1.
- Pearson correlation coefficient between distance and time is 0.81.

# "Butler tracking company" example continued



#### $\mathsf{Model}\ 1$

Is significant p = 0.004, F = 15.1846 whereas  $R^2 = 0.6641$ .

#### Model 2

Is significant p = 0.000276, F = 32.9 whereas adjusted  $R^2 = 0.87$ .

Is it enough to say that model 2 is more precise?

# Quality comparison

- To compare different models *residual sum of squares* (RSS) is used.
- Hypothesis statements:  $H_0: RSS_s \leq RSS_c H_1: RSS_s > RSS_c$ .
- Test statistic (empirical parameter) for ANOVA:

$$F_{stat} = \left(\frac{\text{RSS}_s - \text{RSS}_c}{m}\right) \left(\frac{\text{RSS}_c}{n - p - 1}\right)^{-1}$$

where  $\text{RSS}_c$  is the residuals sum squares of model with more variables,  $\text{RSS}_s$  - is the residuals sum squares of model with less variables, m number of variables added or removed, n is the number of observation points, p - is the number of variables in more complicated model.

- Rejection rule for  $\alpha$  (significance level), degrees of freedom: first is the number of variables added or removed, second is n p 1.
- Decision:
  - (if adding variables) rejected null hypothesis proves that adding variables caused model quality to increase significantly.
  - (if deleting variables) rejected alternative hypothesis proves that deleting variables did not cause model quality to significant decrease.

# "Butler tracking company" example continued

- $RSS_1 = 15.8713$ ,  $RSS_2 = 2.2994$  NB! Observe that corresponding MATLAB notation is SSE!!!
- choose  $\alpha = 0.05$  degrees of freedom: first will be 1 (one variable (number of parcels)) were added, second 7 (n = 10, p = 2).
- Rejection rule: reject  $H_0$  if  $F_{stat} > 5.5914$
- Compute  $F_{stat} = 17.4411$ . (use table, or MATLAB or EXCEL)
- Reject  $H_0$ . Adding the variable has increased the model quality.