# ITC8190 <br> Mathematics for Computer Science Elementary Probability Theory 

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The following slides were borrowed from a lecture material in cryptography course by prof. Ahto Buldas with his permission.
https://courses.cs.ttu.ee/w/images/c/c7/
ITC8240-Unbreakable-ciphers.pdf
$\Omega$-sample space, that contains all possible outcomes $\omega \in \Omega$.


For example, $\Omega=\{$ heads, tails $\}$ for a coin, and $\Omega=\{1, \ldots, 6\}$ for a die.
Events are subsets $A \subseteq \Omega$.
For a die, the event $\{2,4,6\}$ means that the outcome is even.

An event $A$ happens if $\omega \in A$ for the actual outcome $\omega$.


Empty event $\emptyset$ is called the impossible event (it never happens)
$\Omega$ is called the universal event (it always happens)

For every two events $A$ and $B$ we can compute:

| Intersection | $A$ and $B$ | $A \cap B=\{\omega \in \Omega: \omega \in A$ and $\omega \in B\}$ |
| :--- | :--- | :--- |
| Union | $A$ or $B$ | $A \cup B=\{\omega \in \Omega: \omega \in A$ or $\omega \in B\}$ |
| Difference | $A$ but not $B$ | $A \backslash B=\{\omega \in \Omega: \omega \in A$ and $\omega \notin B\}$ |



Inclusion: Event $A$ implies event $A$, if $A \subseteq B$, i.e. if $\omega \in A$ always implies $\omega \in B$. If $A$ happens then $B$ happens.

Exclusion: Events $A$ and $B$ are mutually exclusive if $A \cap B=\emptyset$, i.e. $A$ and $B$ cannot simultaneously happen.


Theorem (1)
$A=(A \backslash B) \cup(A \cap B)$

Proof.
We prove (a) $A \subseteq(A \backslash B) \cup(A \cap B)$ and (b) $(A \backslash B) \cup(A \cap B) \subseteq A$
(a) If $\omega \in A$ then either:

- $\omega \in B$, which implies $\omega \in A \cap B$, or
- $\omega \notin B$, which implies $\omega \in A \backslash B$
(b) If $\omega \in(A \backslash B) \cup(A \cap B)$, then either:
- $\omega \in A \backslash B$, which implies $\omega \in A$, or
- $\omega \in A \cap B$, which also implies $\omega \in A$

Theorem (2)
$A \cup B=(A \backslash B) \cup B$
Proof.
We prove (a) $A \cup B \subseteq(A \backslash B) \cup B$ and (b) $(A \backslash B) \cup B \subseteq A \cup B$
(a) If $\omega \in A \cup B$, then either:

- $\omega \in B$ or
- $\omega \notin B$ and $\omega \in A$, which implies $\omega \in A \backslash B$.
(b) If $\omega \in(A \backslash B) \cup B$ then either:
- $\omega \in B$ or
- $\omega \in A \backslash B$ that implies $\omega \in A$.

The set $\mathcal{F}$ of all events we consider must be a sigma-algebra:

- $\Omega \in \mathcal{F}$
- If $A \in \mathcal{F}$, then $\Omega \backslash A \in F$
- If $A_{1}, A_{2}, A_{3}, \ldots \in \mathcal{F}$, then $A_{1} \cup A_{2} \cup A_{3} \cup \ldots \in \mathcal{F}$

If $A \in \mathcal{F}$, then $A$ is said to be a measurable subset.
Example: The set $P(\Omega)$ of all subsets of $\Omega$ is a sigma-algebra.
In this class, we mostly assume that $\mathcal{F}=P(\Omega)$.

Probability (measure) is a function $\mathrm{P}: \mathcal{F} \rightarrow \mathbb{R}$ such that:

- PM1: $0 \leq \mathrm{P}[A] \leq 1$ for any event $A \in \mathcal{F}$.
- PM2: $\mathrm{P}[\Omega]=1$
- PM3: If $A_{1}, A_{2}, \ldots \in \mathcal{F}$ are mutually exclusive, then

$$
\mathrm{P}\left[A_{1} \cup A_{2} \cup \ldots\right]=\mathrm{P}\left[A_{1}\right]+\mathrm{P}\left[A_{2}\right]+\ldots
$$

The triple $(\Omega, \mathcal{F}, \mathrm{P})$ is called a probability space.
If $\mathcal{F}$ is the set of all subsets of $\Omega$, we omit $\mathcal{F}$ and say that a probability space is a pair $(\Omega, \mathrm{P})$.

Theorem
$\mathrm{P}[\Omega \backslash A]=1-\mathrm{P}[A]$

Proof.
By $P M 2$, we have $\mathrm{P}[\Omega]=1$. As $A$ and $\Omega \backslash A$ are mutually exclusive, and $(\Omega \backslash A) \cup A=\Omega$, by $P M 3$, we have $\mathrm{P}[\Omega \backslash A]+\mathrm{P}[A]=\mathrm{P}[\Omega]=1$ and hence

$$
\mathrm{P}[\Omega \backslash A]=\underbrace{\mathrm{P}[\Omega \backslash A]+\mathrm{P}[A]}_{1}-\mathrm{P}[A]=1-\mathrm{P}[A] .
$$

Theorem
$\mathrm{P}[A]+\mathrm{P}[B]=\mathrm{P}[A \cap B]+\mathrm{P}[A \cup B]$
Proof.
By Thm. 1: $A=(A \backslash B) \cup(A \cap B)$. As $A \backslash B$ and $A \cap B$ are mutually exclusive, by $P M 3$ : $\mathrm{P}[A]=\mathrm{P}[A \backslash B]+\mathrm{P}[A \cap B]$. Hence,

$$
\mathrm{P}[A]+\mathrm{P}[B]=\mathrm{P}[A \backslash B]+\mathrm{P}[B]+\mathrm{P}[A \cap B]
$$

By Thm. 2: $A \cup B=(A \backslash B) \cup B$. As $A \backslash B$ and $B$ are mutually exclusive, by PM3: $\mathrm{P}[A \cup B]=\mathrm{P}[A \backslash B]+\mathrm{P}[B]$. Hence,

$$
\mathrm{P}[A]+\mathrm{P}[B]=\underbrace{\mathrm{P}[A \backslash B]+\mathrm{P}[B]}_{\mathrm{P}[A \cup B]}+\mathrm{P}[A \cap B]=\mathrm{P}[A \cup B]+\mathrm{P}[A \cap B] .
$$

Somehow we learn that an event $B$ (with $\mathrm{P}[B] \neq 0$ ) happens, i.e. $\omega \in B$. Probability space $(\Omega, \mathrm{P})$ collapses to a new space $\left(\Omega^{\prime}, \mathrm{P}^{\prime}\right)$, where $\Omega^{\prime}=B$.


Magnify by $\beta$


We want that there is $\beta$, so that $\mathrm{P}^{\prime}[A]=\beta \cdot \mathrm{P}[A \cap B]$ for any event $A$. As in the new space, $\mathrm{P}^{\prime}[B]=\mathrm{P}^{\prime}\left[\Omega^{\prime}\right]=1$, we have $\beta=\frac{1}{\mathrm{P}[B \cap B]}=\frac{1}{\mathrm{P}[B]}$, i.e.

$$
\mathrm{P}^{\prime}[A]=\frac{\mathrm{P}[A \cap B]}{\mathrm{P}[B]} .
$$

The probability

$$
\mathrm{P}^{\prime}[A]=\frac{\mathrm{P}[A \cap B]}{\mathrm{P}[B]}
$$

is denoted by $\mathrm{P}[A \mid B]$ and is called the conditional probability of $A$ assuming that $B$ happens, i.e.

$$
\mathrm{P}[A \mid B]=\frac{\mathrm{P}[A \cap B]}{\mathrm{P}[B]}
$$

Corollary (Chain Rule):

$$
\mathrm{P}[A \cap B]=\mathrm{P}[B] \cdot \mathrm{P}[A \mid B]=\mathrm{P}[A] \cdot \mathrm{P}[B \mid A]
$$

Random variable $X$ is any function $X: \Omega \rightarrow R$, where $R$ is called the range of $X$. We write $R_{X}$ to denote the range of $X$

For any $x \in R$, we define $X^{-1}(x)$ as the event $\{\omega: X(\omega)=x\}$ and use the notation:

$$
\underset{X}{\mathrm{P}}[x]=\mathrm{P}[X=x]=\mathrm{P}\left[X^{-1}(x)\right] .
$$



In cryptography, we mostly assume that the range $R$ is finite.
Note that if $x \neq x^{\prime}$, then the events $X^{-1}(x)$ and $X^{-1}\left(x^{\prime}\right)$ are mutually exclusive and as $\cup_{x \in R} X^{-1}(x)=\Omega$, we have:

$$
\sum_{x} \underset{X}{\mathrm{P}}[x]=\mathrm{P}\left[\cup_{x \in R} X^{-1}(x)\right]=\mathrm{P}[\Omega]=1
$$

Assume $R$ is finite and $R=\left\{x_{1}, x_{2}, \ldots, x_{n}\right\}$.
The sequence of values $\left(p_{1}, p_{2}, \ldots, p_{n}\right)$, where $p_{i}=\underset{X}{\mathrm{P}}\left[x_{i}\right]$, is called the probability distribution of $X$.


Histograms are graphical representations of probability distributions.


Events $A$ and $B$ are said to be independent if $\mathrm{P}[A \cap B]=\mathrm{P}[A] \cdot \mathrm{P}[B]$ If $\mathrm{P}[A] \neq 0 \neq \mathrm{P}[B]$, then independence is equivalent to:

$$
\mathrm{P}[A \mid B]=\mathrm{P}[A] \quad \text { and } \quad \mathrm{P}[B \mid A]=\mathrm{P}[B]
$$

i.e. the probability of $A$ does not change, if we learn that $B$ happened.

We say that $X$ and $Y$ are independent random variables if for every $x \in R_{X}$ and $y \in R_{Y}$ :

$$
\begin{aligned}
\mathrm{P}[X=x, Y=y] & =\mathrm{P}\left[X^{-1}(x) \cap Y^{-1}(y)\right]=\mathrm{P}\left[X^{-1}(x)\right] \cdot \mathrm{P}\left[Y^{-1}(y)\right] \\
& =\mathrm{P}[X=x] \cdot \mathrm{P}[Y=y]
\end{aligned}
$$

This means that the probability distribution of $X$ does not change, if we learn the value of $Y$, and vice versa

By the direct product $X Y$ (or $(X, Y)$ ) of random variables $X$ and $Y$ on a probability space $(\Omega, \mathrm{P})$ is a random variable defined by

$$
(X Y)(\omega)=(X(\omega), Y(\omega))
$$

Let $X$ be a random variable (with range $R$ ) on a probability space ( $\Omega, \mathrm{P}$ ). If we take $\Omega^{\prime}=R$ and define a probability function $\mathrm{P}_{X}$ on $R$ as follows:

$$
\underset{X}{\mathrm{P}}[A]=\mathrm{P}\left[X^{-1}(A)\right]
$$

where $X^{-1}(A)=\{\omega \in \Omega: X(\omega) \in A\}$, we get a probability space $\left(R, \underset{X}{\mathrm{P}^{\mathrm{P}}}\right)$ that we call a factor space.


To sum up, the chain rule is

$$
\operatorname{Pr}[A \cap B]=\operatorname{Pr}[A \mid B] \cdot \operatorname{Pr}[B]=\operatorname{Pr}[B \mid A] \cdot \operatorname{Pr}[A]
$$

If events $A$ and $B$ are independent, then $\operatorname{Pr}[A \mid B]=\operatorname{Pr}[A]$ and $\operatorname{Pr}[B \mid A]=\operatorname{Pr}[B]$, and the chain rule takes the form of

$$
\operatorname{Pr}[A \cap B]=\operatorname{Pr}[A] \cdot \operatorname{Pr}[B]
$$

The probability of the union

$$
\operatorname{Pr}[A \cup B]=\operatorname{Pr}[A]+\operatorname{Pr}[B]-\operatorname{Pr}[A \cap B] .
$$

If events $A$ and $B$ are mutually exclusive, then
$\operatorname{Pr}[A \cap B]=0$ and hence

$$
\operatorname{Pr}[A \cup B]=\operatorname{Pr}[A]+\operatorname{Pr}[B]
$$

The chain rule

$$
\operatorname{Pr}[A \cap B]=\operatorname{Pr}[A \mid B] \cdot \operatorname{Pr}[B]=\operatorname{Pr}[B \mid A] \cdot \operatorname{Pr}[A]
$$

also provides us with the relationship between conditional probabilities $\operatorname{Pr}[A \mid B]$ and $\operatorname{Pr}[B \mid A]$, namely

$$
\operatorname{Pr}[A \mid B]=\frac{\operatorname{Pr}[B \mid A] \cdot \operatorname{Pr}[A]}{\operatorname{Pr}[B]}
$$

where:
$\operatorname{Pr}[A]$ is the prior belief
$\operatorname{Pr}[B \mid A]$ is called the likelihood
$\operatorname{Pr}[B]$ is called evidence
$\operatorname{Pr}[A \mid B]$ is called the posterior
This is known as the Bayes' theorem. It allows to make informed guesses about observations based on prior knowledge or beliefs.


# THANK YOU FOR <br> YOUR ATTENTION ANY QUESTIONS? 

